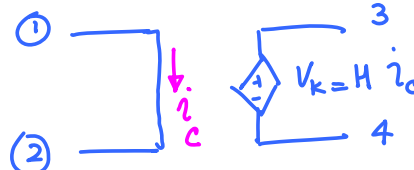


HW # 1 Due Wed Oct. 12

Current controlled source

netlist

H K 3 4 VCONT H

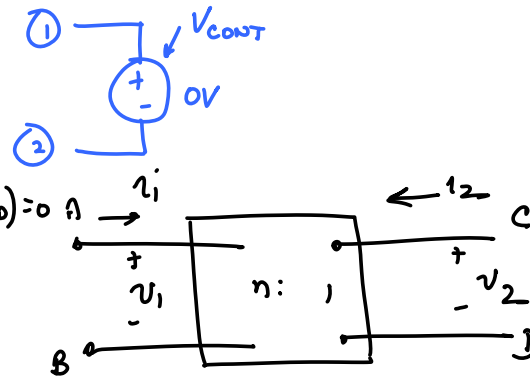


Transformer

$$V_1 = n V_2 : (V_A - V_B) - n (V_C - V_D) = 0$$

$$I_1 = -\frac{1}{n} I_2$$

A	V _A	V _B	V _C	V _D	I ₂
B					
C					
D					



Ber | -1 -n +n |

Gyrator

Nonlinear equation solution

$f(x) = 0$; solution is x^*

$$f'(x^k) (x^{k+1} - x^k) = -f(x^k)$$

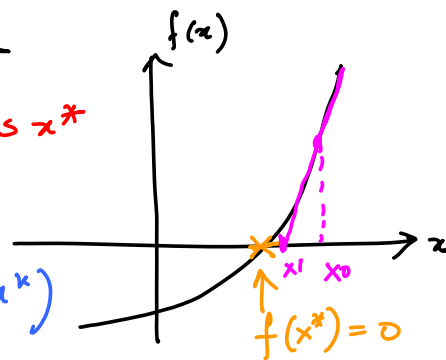
$$x^{k+1} - x^k = -[f'(x^k)]^{-1} f(x^k)$$

$$x^{k+1} = x^k - [f'(x^k)]^{-1} f(x^k)$$

$\frac{\partial f}{\partial x} \Big|_{x^k}$

$\frac{\partial f}{\partial x}$ is bounded away from zero

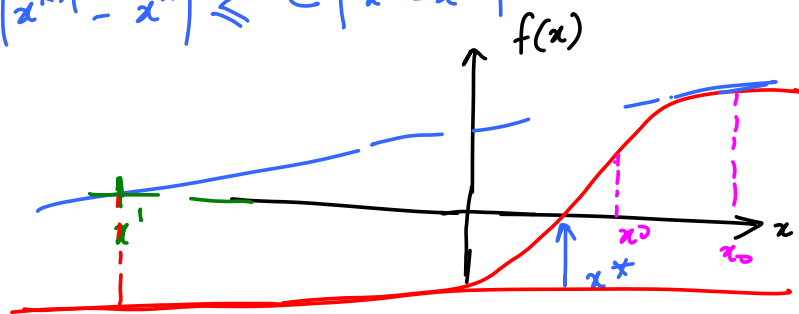
$\frac{\partial^2 f}{\partial x^2}$ is bounded



if x^0 was sufficiently close to x^*

Then Newton's method converges to the solution and the convergence rate is quadratic

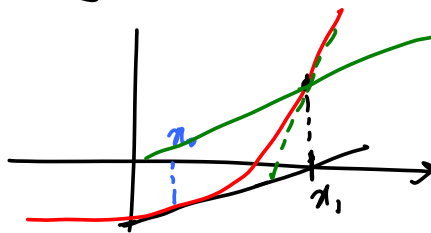
$$|x^{k+1} - x^*| \leq c |x^k - x^*|^2$$



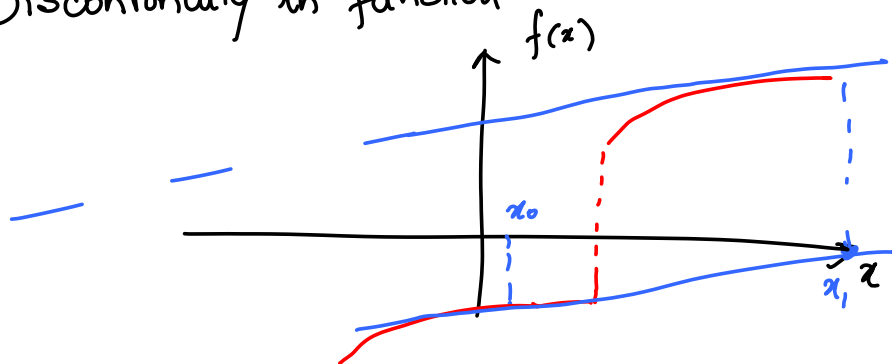
Potential problems:

1) x^0 is not close enough to x^*

2) Error in derivative



3) Discontinuity in function

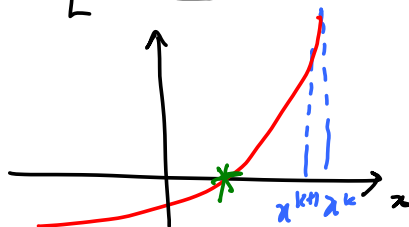


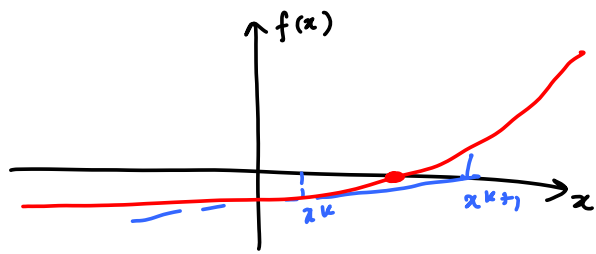
Convergence checks

$$(x^{k+1} - x^k) = - [f'(x^k)]^{-1} f(x^k)$$

$$\|x^{k+1} - x^k\| < \text{tolerance}$$

$$\|f(x)\| < \text{tolerance}$$





Multidimensional case

$$\left. \begin{array}{l} \text{KCL} \\ \text{equations} \end{array} \right\} \begin{array}{l} f_1(x_1, x_2, \dots, x_n) = 0 \\ \vdots \\ f_n(x_1, x_2, \dots, x_n) = 0 \end{array}$$

$$J(\underline{x}^k) (\underline{x}^{k+1} - \underline{x}^k) = -f(\underline{x}^k)$$

$$J(\underline{x}^k) = \left[\begin{array}{cccc} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \frac{\partial f_n}{\partial x_2} & \dots & \frac{\partial f_n}{\partial x_n} \end{array} \right] \Bigg|_{\underline{x}^k}$$

Computational Procedure

1) Evaluate $f(\underline{x}^k)$ and $J(\underline{x}^k)$ ←

2) Assemble circuit equations

$$J(\underline{x}^k) (\underline{x}^{k+1} - \underline{x}^k) = -f(\underline{x}^k)$$

OR

$$J(\underline{x}^k) \underline{x}^{k+1} = J(\underline{x}^k) \underline{x}^k - f(\underline{x}^k)$$

$$A \underline{x} = b \quad \text{linear system of equations}$$

3) Do not compute the inverse of $J(\underline{x}^k)$ instead solve the linear equations using LU factorization & F/B solves (+ sparse matrix techniques)

4) Solution gives \underline{x}^{k+1} (or $\Delta \underline{x}^{k+1}$)

5) Repeat procedure until convergence
or exceeds Maximum # of iterations
(default in SPICE 100)

Remarks :

- Since the device equations are known, the derivatives can be computed explicitly (or as equations)
- Automatic differentiation
- The significant computational cost/iteration
 $J(x^k), f(x^k)$ ← model evaluation
 Solve $Ax = b$ ← linear eqn. solution

This can be a significant cost in very complex models

- Some versions of SPICE will skip model evaluation at every iteration
(BYPASS = 1)

Application to circuits :

$$f(x) = x_1 + x_2 + x_3 = 0$$

Linearize per Newton's method

$$\left. \frac{\partial f}{\partial x} \right|_{x^k} (x^{k+1} - x^k) = -f(x^k)$$

$$\left. \frac{\partial f}{\partial x} \right|_{x^k} x^{k+1} = \left. \frac{\partial f}{\partial x} \right|_{x^k} x^k - f(x^k)$$

Linearization of linear equations → no change

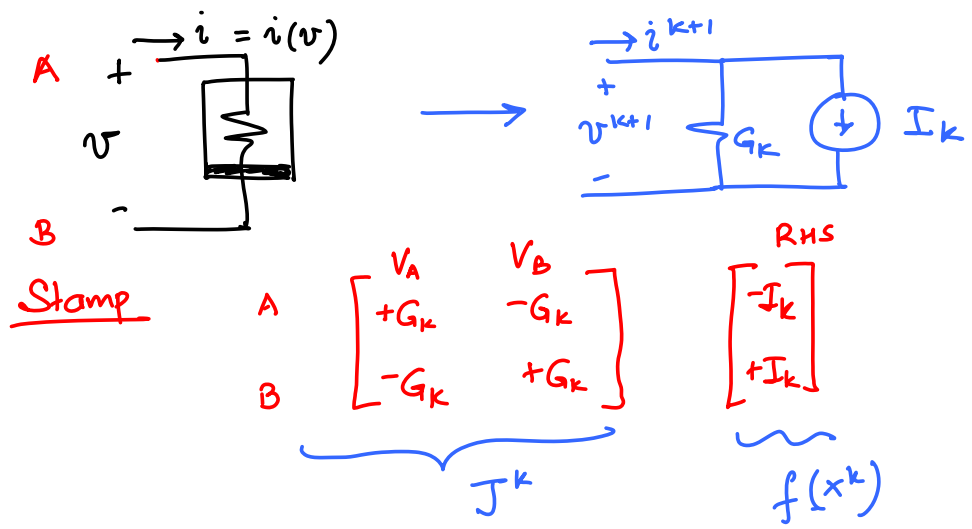
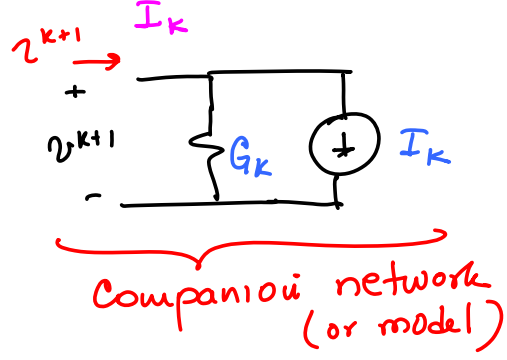
What about a nonlinear resistor?

$$i = i(v)$$

$$v^{k+1} = v^k + \underbrace{\frac{\partial i}{\partial v}}_{G_k} \bigg|_{v^k} (v^{k+1} - v^k)$$

$$v^{k+1} = G_k (v^{k+1} - v^k) + i^k$$

$$= \underbrace{G_k}_{I_k} v^{k+1} + \underbrace{i^k - G_k v^k}_{I_k}$$



Diode

$$i = I_s (e^{v/v_{th}} - 1)$$

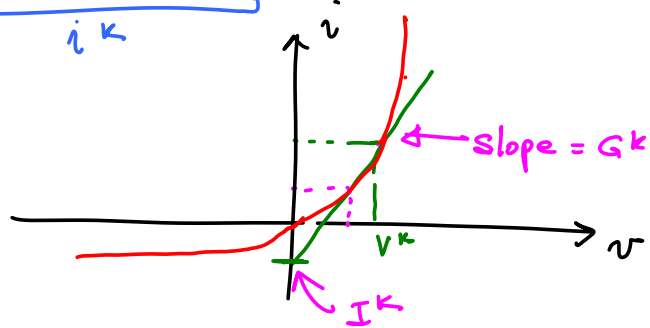
I_s and v_{th} are constants at a given temp.

$$G_k = \frac{\partial i}{\partial v} \bigg|_{v^k}$$

$$I_k = i^k - G_k v^k$$

$$G_k = \frac{I_s}{V_{th}} e^{v/v_{th}} \Big|_{v=v^k}$$

$$I_k = \underbrace{I_s (e^{v^k/V_{th}} - 1)}_{i_k} - G_k v^k$$

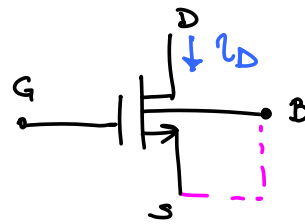


MOSFET

V_{GS}, V_{DS}

In saturation:

$$i_D = \frac{K'}{2} \frac{W}{L} (V_{GS} - V_T)^2 (1 + \lambda V_{DS})$$



↳ Level-1 MOS model

$$i_D = f(V_{GS}, V_{DS})$$

$$i_D^{k+1} = i_D^k + \underbrace{\frac{\partial i_D}{\partial V_{GS}} \Big|_{V_{GS}^k, V_{DS}^k}}_{g_m^k} (V_{GS}^{k+1} - V_{GS}^k)$$

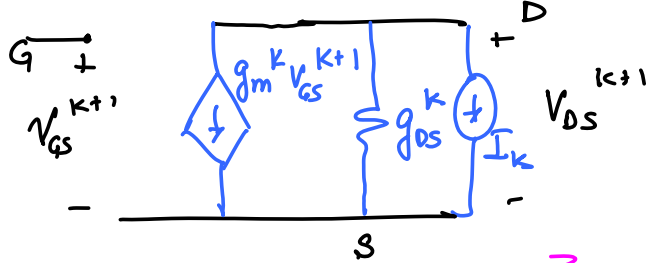
$$+ \underbrace{\frac{\partial i_D}{\partial V_{DS}} \Big|_{V_{DS}^k, V_{GS}^k}}_{g_{DS}^k} (V_{DS}^{k+1} - V_{DS}^k)$$

$$\rightarrow i_D^{k+1} = i_D^k + g_m^k (V_{GS}^{k+1} - V_{GS}^k) + g_{DS}^k (V_{DS}^{k+1} - V_{DS}^k)$$

$$g_m^k = \frac{K'}{L} W (V_{GS} - V_T) (1 + \lambda V_{DS}) \Big|_{V_{GS}^k, V_{DS}^k}$$

$$g_{DS}^k = \frac{K'}{2} \frac{W}{L} (V_{GS} - V_T)^2 \lambda \Big|_{V_{GS}^k, V_{DS}^k}$$

$$I_D^{k+1} = g_m^k V_{GS}^{k+1} + g_{DS}^k V_{DS}^{k+1} + I_k - g_m^k V_{GS}^k - g_{DS}^k V_{DS}^k$$

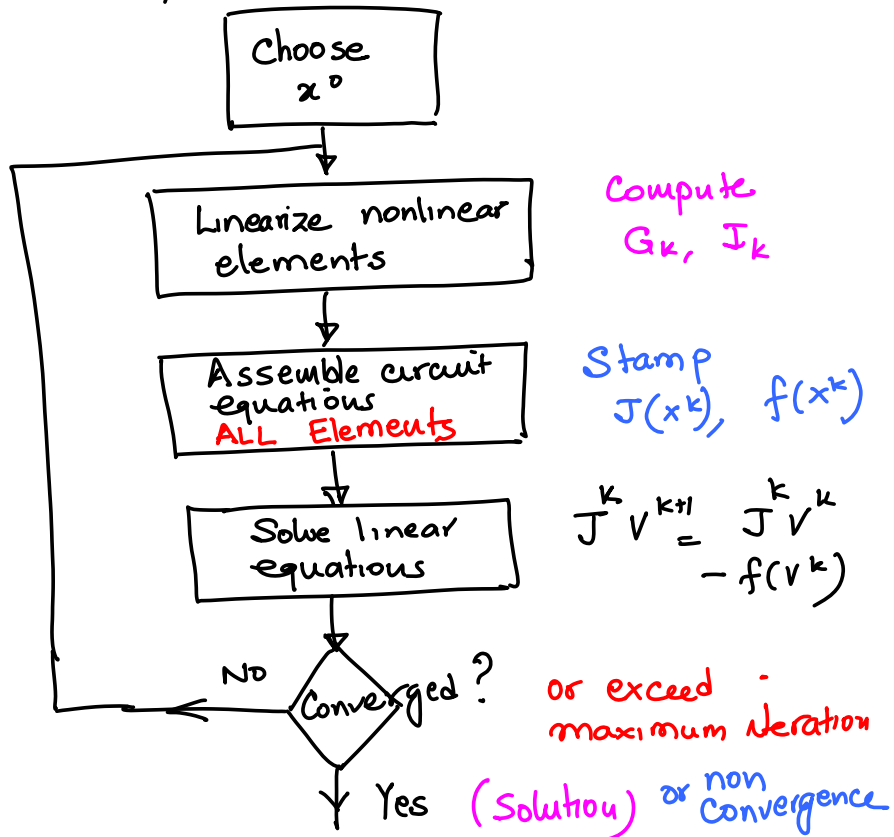


Companion network for MOSFET

Stamp

	V_D	V_S	V_G	RHS
D	$+g_{DS}^k$	$-g_{DS}^k - g_m^k$	$+g_m^k$	$-I_k$
S	$-g_{DS}^k$	$+g_{DS}^k + g_m^k$	$-g_m^k$	$+I_k$
G	0	0	0	0

SPICE DC analysis



SPICE Convergence Checks

For each node:

$$|V^{k+1} - V^k| \leq \underset{\substack{\uparrow \\ \text{VNTOL}}}{\epsilon_A} + \epsilon_R \underset{\substack{\uparrow \\ \text{RELTOL}}}{\text{MAX}(|V^k|, |V^{k+1}|)}$$

Default values: $\text{VNTOL} = 10^{-6}$ (1 μV)
 $\text{RELTOL} = 10^{-3}$

SPICE doesn't do a convergence check on $|f(x)|$

Instead:

$$|I_k - \hat{I}_k| \leq \underset{\substack{\uparrow \\ \text{ABSTOL}}}{\epsilon_A} + \epsilon_R \text{MAX}(|I_k|, |\hat{I}_k|)$$

Default value of $\text{ABSTOL} = 10^{-12}$ (1pA)

$I_k =$ actual current for voltage V^k

$\hat{I}_k =$ linearized terminal current for V^k
numerical overflow issues
Limiting methods!

