

HW #3 - Part 1 Due today

HW #4 - part 2 Due Wednesday
Project proposals " Monday Nov. 21

Graded HW #3 - Part 2 handed back

Sample exam posted on class website
Exam Mon Nov. 21
(more on Wednesday)

```
int *rcheck;
pnjlim (          rcheck)
```

```
double pnjlim( - - - rcheck)
int * rcheck;
```

```
double pnjlim();
```

```
vnew = pnjlim(          );
```

BJT

```
pnjlim (Vbe
pnjlim (Vbc
```

out of bound arrays;

$$I_c^k = f(v^k) - g_{mf} V_E - - -$$

$$= I_c - g_{mf} V_{be} + \frac{g_{mr}}{\alpha_R} V_{bc}$$

$$I_E^k = I_E + \frac{g_{mf}}{\alpha_F} V_{be} - g_{mr} V_{bc}$$

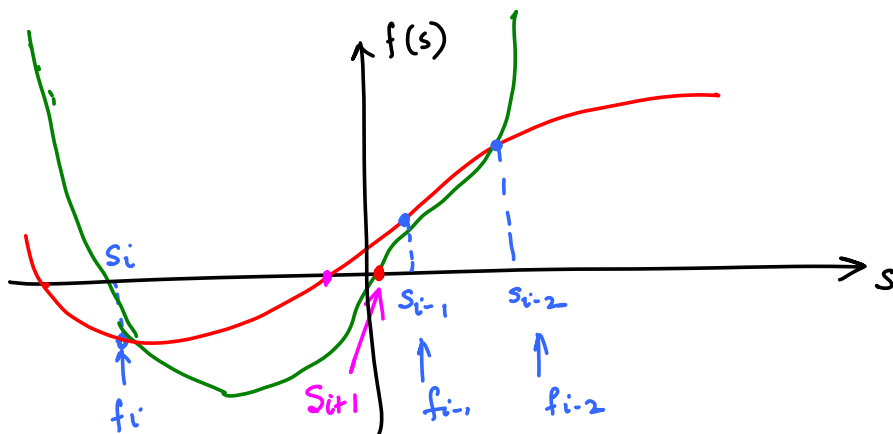
Pole/zero analysis

$$\det(G + sC) = 0 \rightarrow \text{poles}$$

$$\det(G_a + sC_a) = 0 \rightarrow \text{zeros}$$

Finding the roots of polynomials

Muller's method $F(s) = a_0 + a_1 s + a_2 s^2 + \dots + a_n s^n$



$$b_0 + b_1 s + b_2 s^2$$

Note that this process relies on calculating $f(s_i)$
which is $\det(G + s_i C)$. $s_i = \sigma_i + j\omega_i$

$$A = LU$$

$$\det(A) = \det(LU) = \det(L) \det(U)$$

$$L = \begin{bmatrix} l_{11} & & & \\ l_{21} & l_{22} & & \\ \vdots & & \ddots & \\ l_{m1} & & & l_{nn} \end{bmatrix} \quad U = \begin{bmatrix} 1 & u_{12} & \dots & u_{1n} \\ & 1 & & \\ & & \ddots & \\ & & & u_{n-1,n} \\ & & & & 1 \end{bmatrix}$$

$$\det(L) = l_{11} l_{22} \dots l_{nn}$$

$$\det(U) = 1$$

$$\det(G + s_i C) = l_{11} l_{22} \dots l_{nn} \quad (\text{small-signal})$$

→ In the simulator a circuit load is performed for a value of $s = s_i$

→ LU factors the circuit matrix

Remarks

- SPICE2 doesn't support .pz analysis
- SPICE3 uses Muller's method
HSPICE
- Muller's method is not very robust
HSPICE has many options!

QZ algorithm

standard algorithm

Solves the generalized eigenvalue problem

$$Ax = \lambda x \quad \text{eigenvalue problem}$$

$$Ax = \lambda Bx \quad \text{generalized}$$

$$\begin{matrix} \uparrow & \uparrow \\ \text{matrix} & \text{matrix} \end{matrix}$$

$$Ax - \lambda Bx = 0$$

$$\det(A - \lambda B) = 0$$

$$\det(G + sC) = 0$$

QZ algorithm is a dense matrix algorithm

⇒ cannot be used for circuits with > 500 nodes

What do we do for larger circuits?

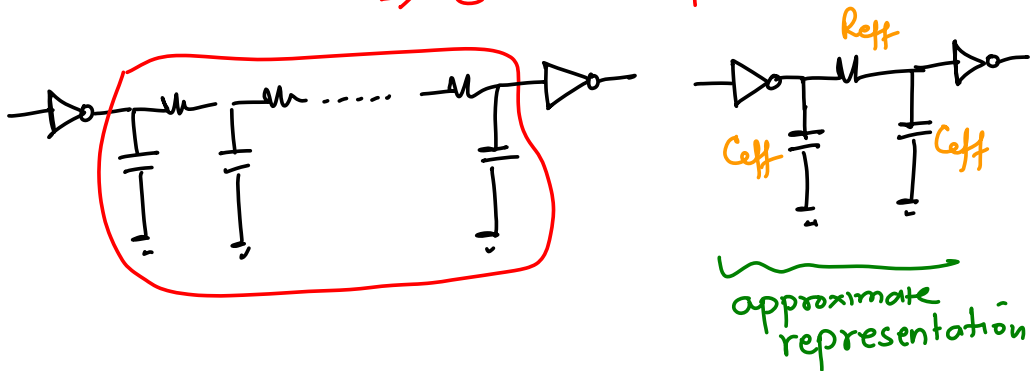
Q1: Do we really need all of the poles of a circuit 10000 nodes \sim 10000 poles

Q2: Even if we could determine all the poles then what does one do with that info?

Observation

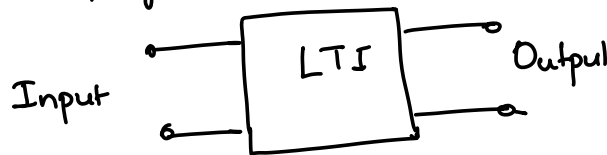
only a small number of poles are important for characterizing circuit performance

\Rightarrow dominant poles



\rightarrow Asymptotic Waveform Evaluation (AWE)
Padé via Lanczos (PVL)

The underlying idea is that of Padé approx.



The input/output relationship is described by a transfer function

$$H(s) = \frac{a_0' + a_1' s + a_2' s^2 + \dots + a_m' s^m}{b_0' + b_1' s + b_2' s^2 + \dots + b_n' s^n}$$

Approximate the transfer function as

$$H_{pq}(s) = \frac{a_0 + a_1 s + a_2 s^2 + \dots + a_p s^p}{1 + b_1 s + b_2 s^2 + \dots + b_q s^q}$$

where $p < m$, $q < n$

$H_{p,q}(s)$ is the Padé approx of $H(s)$ of type $[P/Q]$

Defn A Padé approximant of $F(s)$ is denoted by

$$[P/Q] = \frac{N_p(s)}{D_q(s)}$$

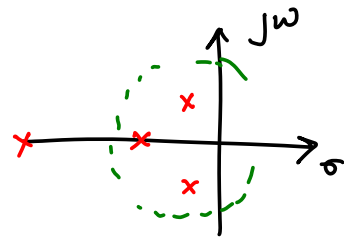
Consider $H(s)$ with distinct poles p_1, p_2, \dots, p_n

$$H(s) = \sum_{i=1}^n \frac{k_i}{s-p_i}$$

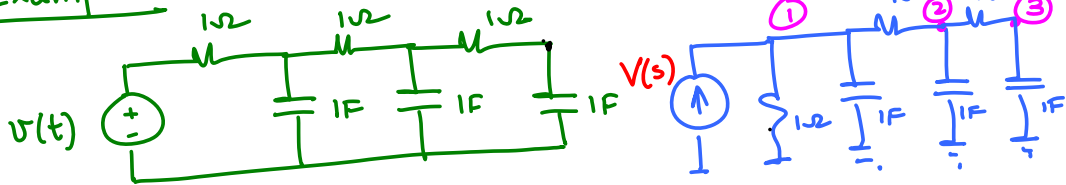
$$h(t) = \sum_{i=1}^n k_i e^{p_i t}$$

$$H_{p,q}(s) = \sum_{i=1}^q \frac{k'_i}{s-p'_i}$$

$$\tilde{h}(t) = \sum_{i=1}^q k'_i e^{p'_i t}$$



Example



$$\begin{bmatrix} 2+s & -1 & 0 \\ -1 & 2+s & -1 \\ 0 & -1 & 1+s \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} I(s) \\ 0 \\ 0 \end{bmatrix}$$

$$H(s) = \frac{V_3(s)}{V(s)} = \frac{1}{s^3 + 5s^2 + 6s + 1}$$

For $V(s) = \frac{1}{s}$, i.e. a step function

$$V_3(s) = \frac{1}{s(s^3 + 5s^2 + 6s + 1)}$$

$$= \frac{k_1}{s} + \frac{k_2}{s+3.247} + \frac{k_3}{s+1.555} + \frac{k_4}{s+0.1981}$$

$$v(t) = 1 - 0.0597 e^{-3.247t} + 0.2801 e^{-1.555t} - \underline{\underline{1.2204 e^{-0.1981t}}}$$

Pade approximations

$$[0/1] = \frac{a_0}{1+b_1s} = \frac{1}{s^3+5s^2+6s+1}$$

$$a_0 = 1; \quad b_1 = 6$$

$$= \frac{1}{1+6s}$$

$$[1/2] = \frac{a_0 + a_1s}{1 + b_1s + b_2s^2} = \frac{1}{s^3 + 5s^2 + 6s + 1}$$

$$(a_0 + a_1s)(s^3 + 5s^2 + 6s + 1) = 1 + b_1s + b_2s^2$$

$$a_0 = 1$$

$$a_1 + 6a_0 = b_1$$

$$+6a_1 + 5a_0 = b_2$$

$$a_0 + 5a_1 = 0$$

$$\Rightarrow \quad a_1 = \underline{\underline{-\frac{1}{5}}} \quad b_1 = \underline{\underline{\frac{29}{5}}} \quad b_2 = \underline{\underline{\frac{19}{5}}}$$

$$H_{1,2}(s) = \frac{1 - \frac{1}{5}s}{1 + \frac{29}{5}s + \frac{19}{5}s^2}$$

Step input: $V_3(s) = \frac{K_1}{s} + \frac{K_2}{s+1.3282} + \frac{K_3}{s+0.1981}$

$$v(t) = 1 + 0.2219 e^{-1.3282t} - \underline{\underline{1.2219 e^{-0.1981t}}}$$

A Pade' approximant of $F(s)$ is

$$[P/q] = \frac{N_p(s)}{D_q(s)}$$

Pade' table

		p			
		0	1	2	...
q	0	[0/0]	[1/0]	[2/0]	
	1	[0/1]	[1/1]	[2/1]	
	2	[0/2]	[1/2]	[2/2]	
	⋮				

AWE McLaurin series expansion

$$F(s) = \underline{m_0} + \underline{m_1}s + \underline{m_2}s^2 + \dots = \sum_{i=0}^{\infty} m_i s^i$$

m_i is called the i th moment

Recall

$$F(s) = \int_0^{\infty} f(t) e^{-st} dt \quad \text{Laplace transform}$$

$$= \int_0^{\infty} f(t) \left[1 - st + \frac{(st)^2}{2!} - \frac{(st)^3}{3!} + \dots \right] dt$$

$$= \int_0^{\infty} f(t) dt - s \int_0^{\infty} t f(t) dt + \frac{s^2}{2!} \int_0^{\infty} t^2 f(t) dt$$

$$m_0 = \int_0^{\infty} f(t) dt ; \quad m_i = \frac{(-1)^i}{i!} \int_0^{\infty} t^i f(t) dt$$

Suppose m_0, m_1, m_2, \dots are known. Then consider the $[q-1/q]$ Pade' approximant

$$m_0 + m_1 s + m_2 s^2 + m_3 s^3 + \dots + m_{2q-1} s^{2q-1} = \frac{a_0 + a_1 s + a_2 s^2 + \dots + a_{q-1} s^{q-1}}{1 + b_1 s + b_2 s^2 + \dots + b_q s^q}$$

$$s^0: \quad a_0 = m_0$$

$$s^1: \quad a_1 = m_1 + m_0 b_1$$

$$s^2: \quad a_2 = m_2 + m_1 b_1 + m_0 b_2$$

$$\vdots$$

$$s^{q-1}$$

$$s^q \quad 0 = m_q + m_{q-1} b_1 + m_{q-2} b_2 + \dots + m_0 b_q$$

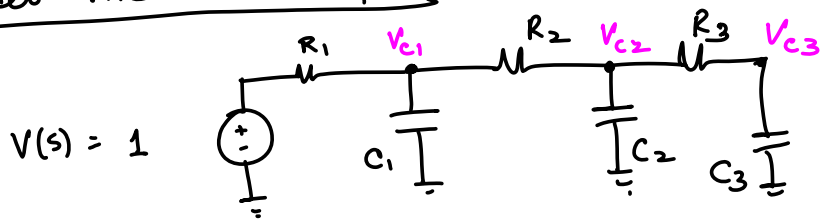
$$s^{2q-1} \quad 0 = \begin{bmatrix} m_0 & m_1 & \dots & m_{q-1} \\ m_1 & m_2 & \dots & m_q \\ m_2 & m_3 & \dots & m_{q+1} \\ \vdots & \vdots & \ddots & \vdots \\ m_{q-1} & m_q & \dots & m_{2q-1} \end{bmatrix} \begin{bmatrix} b_q \\ b_{q-1} \\ \vdots \\ b_1 \end{bmatrix} = \begin{bmatrix} m_q \\ m_{q+1} \\ \vdots \\ m_{2q-1} \end{bmatrix}$$

How do we compute the moments?

These are moments of the impulse response

$$v(t) = \delta(t) \Rightarrow V(s) = 1$$

Consider the RC example



Expressing V_{c1} , V_{c2} , V_{c3} as an infinite power series

$$V_{c1} = m_0^{c1} + m_1^{c1} s + m_2^{c1} s^2 + \dots$$

$$V_{c2} = m_0^{c2} + m_1^{c2} s + m_2^{c2} s^2 + \dots$$

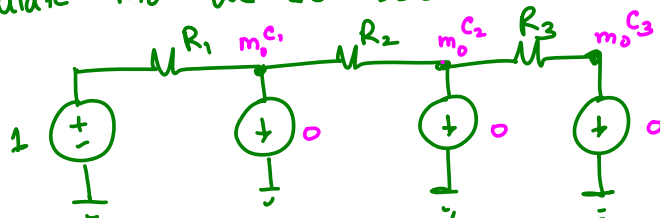
$$V_{c3} = m_0^{c3} + m_1^{c3} s + m_2^{c3} s^2 + \dots$$

Current through capacitor C_i

$$I^{c_i} = s C_i V_{c_i}$$

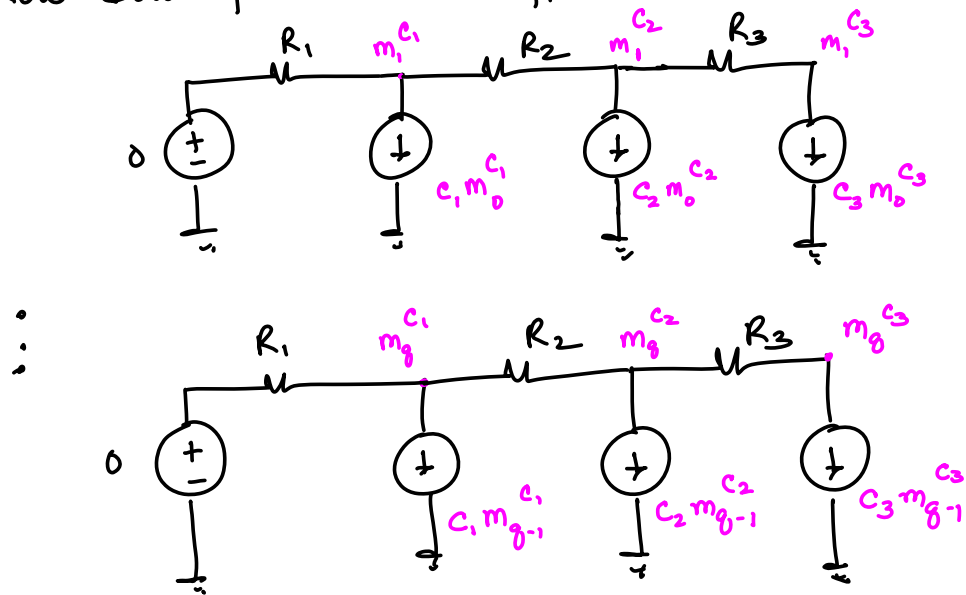
$$= s C_i \left[m_0^{c_i} + m_1^{c_i} s + m_2^{c_i} s^2 + \dots \right]$$

To calculate m_0 we set $s=0$



$$\Rightarrow m_0^{c1}, m_0^{c2}, m_0^{c3} \text{ are known} \\ = 1$$

Now solve for the s^i coefficients



- We are obtaining the dc solution of a network with capacitors replaced by indep current sources (inductors \rightarrow indep voltage srcs)

- For each moment calculation the circuit topology remains the same. Only the RHS changes

\Rightarrow LU factor circuit matrix & solve using forward/back solves for different RHS

RC Example

$$m_0(1) = 1$$

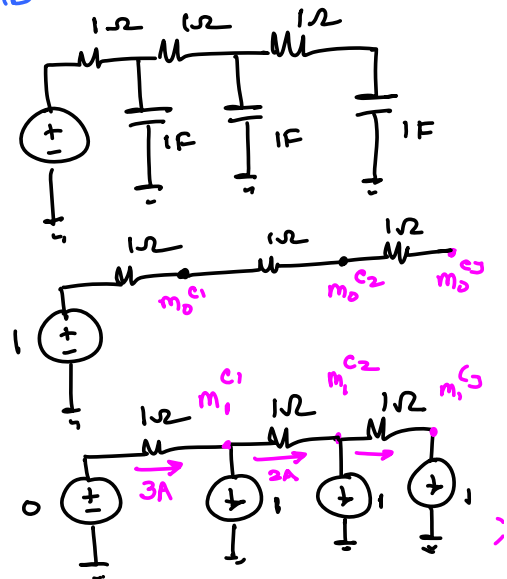
$$m_0(2) = 1$$

$$m_0(3) = 1$$

$$m_1(1) = -3$$

$$m_1(2) = -5$$

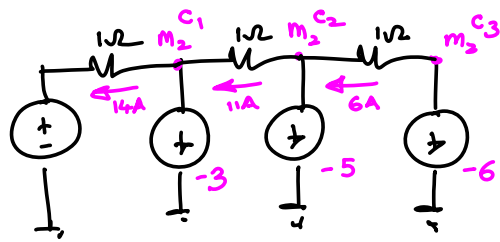
$$m_1(3) = -6$$



$$m_2(1) = 14$$

$$m_2(2) = 25$$

$$m_2(3) = 31$$



$$V_3(s) = 1 - 6s + 31s^2 - 157s^3$$

$$[1/2] : \quad = \frac{a_0 + a_1 s}{1 + b_1 s + b_2 s^2}$$

$$(1 - 6s + 31s^2 - 157s^3)(1 + b_1 s + b_2 s^2) = a_0 + a_1 s$$

$$a_0 = 1$$

$$a_1 = b_1 - 6$$

$$0 = b_2 - 6b_1 + 31$$

$$0 = \dots$$

$$\left. \begin{array}{l} b_1 = 29/5 \\ b_2 = 19/5 \\ a_1 = -1/5 \end{array} \right\}$$