

Debouncing Switches

- ▶ Mechanical switches are one of the most common interfaces to a uC.
- ▶ Switch inputs are asynchronous to the uC and are not electrically clean.
- ▶ Asynchronous inputs can be handled with a synchronizer (2 FF's).
- ▶ Inputs from a switch are electrically cleansed with a switch debouncer.
- ▶ This can also be done with software.
- ▶ What is switch bounce?
 - ▶ The non-ideal behavior of the contacts that creates multiple electrical transitions for a single user input.



Figure 1: Contact Closure is Anything but Simple

Debouncing Switches

- Falling and rising edge switch bounce from a pushbutton switch

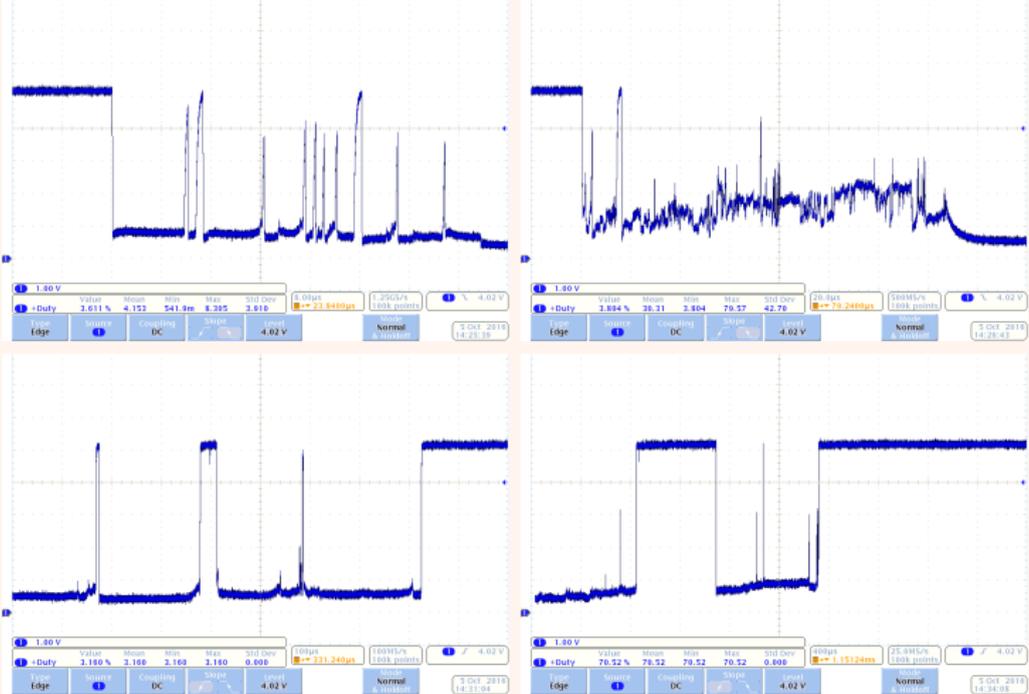


Figure 2: Either Edge Can Bounce

Debouncing Switches

- ▶ The problem is that the uC is usually fast enough to see all the transitions
- ▶ uC acts on multiple transitions instead of a single one
- ▶ The oscilloscope traces showed bounce durations of 10-300us
- ▶ Our mega128 uC runs at 62.5ns per instruction
- ▶ A 10uS bounce (short) is $(1 \times 10^{-5} / 62.5 \times 10^{-9})$ 160 instructions long!
- ▶ A 100uS bounce could be sampled as a valid true or false 100s of times
- ▶ Results are incorrect behavior as seen by user

Debouncing Switches

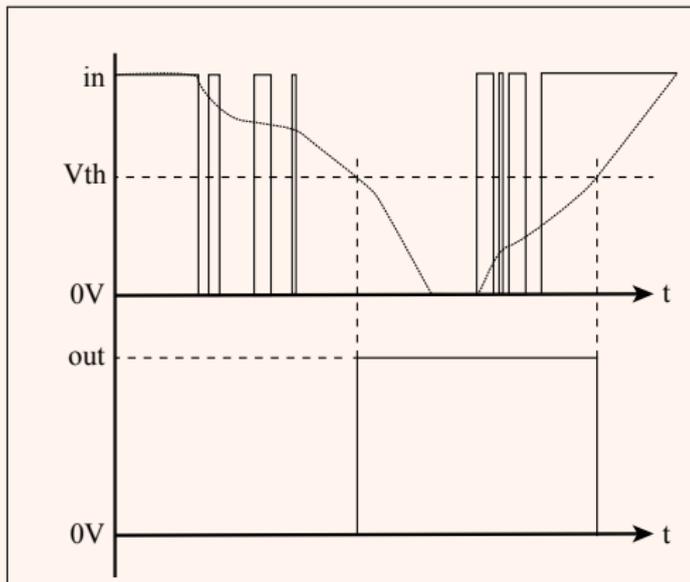
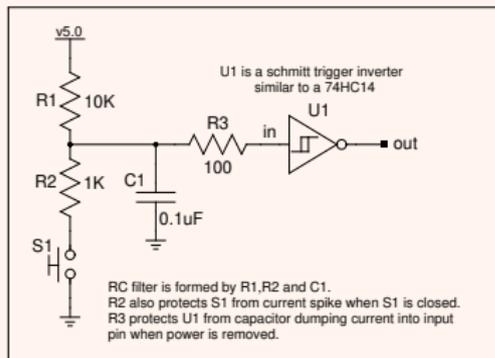
- ▶ Characteristics of switch bounce:
 - ▶ Nearly all switches do it
 - ▶ The duration of bouncing and the period of each bounce varies
 - ▶ Switches of exactly the same type bounce differently
 - ▶ Bounce differs depending on user force and speed
 - ▶ Typical bounce frequency is 100us-10ms

■ Specifications		
Type	Snap action / Push-on type SPST	
Electrical	Rating	10 μ A 2V DC to 50mA 12V DC (Resistive load)
	Contact Resistance	500m Ω max.
	Insulation Resistance	100M Ω min. (at 100V DC)
	Dielectric Withstanding Voltage	250V AC for 1 minute
	Bouncing	10ms max. (ON, OFF)

Figure 3: Specifications for Panasonic EVP-BD6C1A000 pushbutton switch

Debouncing Switches

- ▶ One possible solution - Analog filtering
- ▶ RC network filters out the rapid changes in switch output
- ▶ Choose R and C so input threshold is not crossed while input is still bouncing



Debouncing Switches

- ▶ Software solutions
 - ▶ Need to minimize CPU usage and be independent of CPU clock speed
 - ▶ Use constant defines in makefile to remove speed dependencies
 - ▶ Don't use interrupt pins, only periodic polling
 - ▶ Don't synchronously scan noisy devices
 - ▶ Quickly identify initial switch closure (100mS max)

Debouncing Switches

► Count-based software solution

```
//source: Jack Gansel, "Guide to Debouncing"  
//returns '1' once per button push, detects falling edge  
uint8_t debounce_pulse() {  
    static uint16_t state  
    state = (state << 1) | (! bit_is_clear(PIND, 2)) | 0xE000;  
    if (state == 0xF000) return 1;  
    return 0;  
}
```

Which pass	Value of state	Return value
first pass after reset	1110 0000 0000 0001	return 0
second pass after reset	1110 0000 0000 0011	return 0
after 12 false passes	1111 1111 1111 1111	return 0
after 7 true passes	1111 1111 1000 0000	return 0
after 12 true passes	1111 0000 0000 0000	return 1
after many true passes	1110 0000 0000 0000	return 0
after 5 false passes	1110 0000 0001 1111	return 0

Debouncing Switches

- Solution based on digital 1st-order recursive low-pass filter

```
//Acts like RC filter followed by schmitt trigger
//continuous output like an analog switch
// 0.25=0x3F, 0.75=0xC0, 1.0=0xFF
int8_t debounce_cont(){
    static uint8_t y_old=0, flag=0;
    uint8_t temp;

    //digital filter: y_old=x_new*0.25 + y_old*0.75
    temp = (y_old >> 2); //yields y_old/4
    y_old = y_old - temp; //(y_old*0.75) by subtraction
    //if button pushed, add 0.25
    if(bit_is_clear(PIND,2)){y_old = y_old + 0x3F;}

    //software schmitt trigger
    if((y_old > 0xF0) && (flag==0)){flag=1; return 1;}
    if((y_old < 0x0F) && (flag==1)){flag=0; return 0;}
    return (-1); //no change from last time
}
```

Debouncing Switches

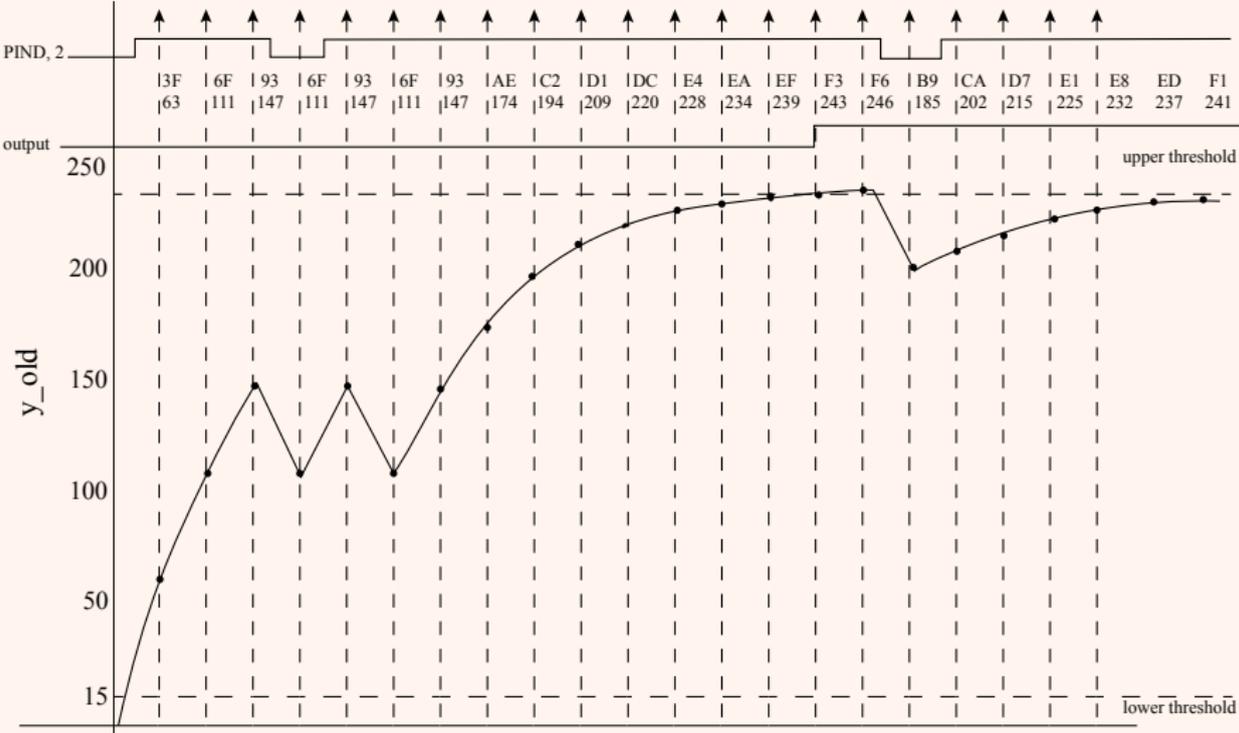


Figure 4: Behavior of IIR Filter with Schmitt Trigger

Debouncing Switches

- ▶ Sometimes we want an output that is continuous for as long as the switch contacts are in their active state. For example, the keys on an electronic keyboard.
- ▶ Other times we want a momentary or pulsed output, such as a button that increments the hour alarm on a clock.
- ▶ The first count-based debouncer (Gansel) gave a pulsed output.
- ▶ The digital filter algorithm gives a continuous output.

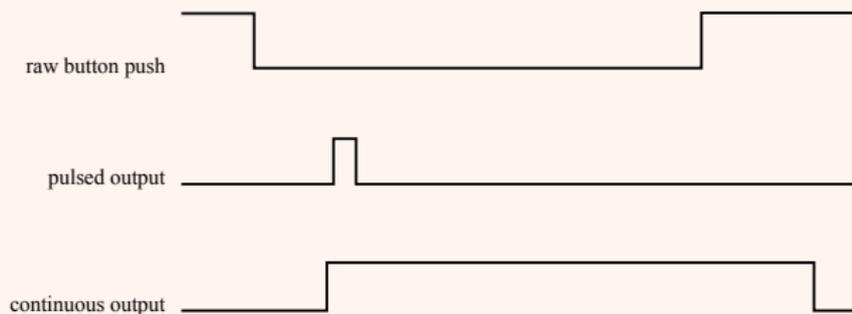
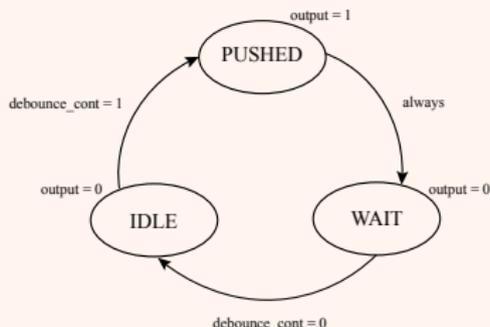


Figure 5: Pulsed versus Continuous Output

Debouncing Switches

- ▶ How would you convert between types of debouncer output?
- ▶ Use a state machine to get a pulsed output from a continuous debouncer.

```
//state machine returns one pulse for each push and release
static enum button_state_type{IDLE, PUSHED, WAIT} state;
switch(state){
  case(IDLE)  :output=0; if(debounce_cont()){state=PUSHED;} break;
  case(PUSHED):output=1;                state=WAIT;    break;
  case(WAIT)  :output=0; if(~debounce_cont()){state=IDLE;} break;
  default    :                :                break;
} //switch
```



Debouncing Switches

- ▶ A state machine for continuous output from a pulsed debouncer.
- ▶ This scheme requires rising and falling edge detection.

```
//2 state state machine returns continuous output
static enum button_state_type{OFF, PUSH} state;
switch(state){
    case(OFF) :          if(rising_edge() ){state=PUSH;} break;
    case(PUSH): output=1; if(falling_edge()){state=OFF;} break;
    default      :          break;
} //switch
```

